

SKF @ptitude Observer v13.3 release summary



REQUIREMENTS



Software & FW requirements in Observer v.13.3

- Recommended IMx-1 GW firmware version 4.0
- Recommended IMx-1 Sensor firmware version 4.1
- Recommended IMx firmware version 7.8
- Monitor Service requires 64-bit OS

Deprecated functions

 OPC Classic interface is deprecated and will be automatically converted to OPC UA

Feature obsolescence plan in future releases

- Message centre (disabling is planned for the next release)
- OPC UA Internal Build-in Server: Publishing Dynamic Data (disabling is planned for next release)



NEW FEATURES

Measurement location

- Measurement location is a new feature for a visual representation of vibration sensor position on the machine's photo/drawings.
- This functionality will help with the mapping of the machine's parts to device measurement channels/points.
- User can upload machine photos and set this mapping from the Machine parts view and later open this Measurement Location view from the toolbar during analysis.

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• This feature can be used for mapping IMx Wired, IMx-1 and Microlog measurement points/channels.





Phoenix API: new Measurement Location endpoints

- Information about *Measurement Locations* as well can be extracted via the Phoenix API interface.
- We've introduced two new endpoints:
 - GET v1/measurement-locations returns a list of all Measurement locations in DB
 - GET v1/machines/{machineId}/measurement-locations returns all Measurement Locations for a particular machine.

| GET /v1/measurement-locations Returns a li | ist of all Measurement Locations | GET /v1/mach | hines/{machineId}/measurement-locations | Ret | urns all Measureme | ent Locations for a particular machine |
|--|----------------------------------|--|--|--|------------------------|--|
| Implementation Notes Returns all Measurement Locations in the system | | Implementation Returns all Measu Response Class OK | Notes urement Locations for the given machine s (Status 200) | | | |
| Response Class (Status 200) OK | | Model Example V | Value | | | |
| Model Example Value Inline Model [MeasurementLocation | | MeasurementLoc] MeasurementLoca id (integer, option | ation tion { alion location, locatio | | | |
|] MeasurementLocation { id (integer, optional): ID of the measurement location, machineld (integer, optional): ID of the machine that this measurement location belongs to | | machineld (integ name (string, opti pointPartMappin measurement loc | er, optional): ID of the machine that this measurement ional): User defined name of this measurement location igs (Array[CM.Phoenix.Model.v1.MeasurementLocation ation | location belongs to, n, n.PointPartMapping], <i>optional</i>): Li | ist of Point Part maj | ppings that belong to this |
| name (string, optional): User defined name of this measurement location. PointPartMapping], optional): List of Point Part mapping measurement location. PointPartMapping], optional): List of Point Part mapping measurement location | s that belong to this | CM.Phoenix.Model pointIds (Array[int partIds (Array[int | I.v1.MeasurementLocation.PointPartMapping { hteger], optional): IDs of the measurement points that a eger], optional): IDs of the machine parts that are asso | re associated with this mapping, ciated with this mapping | | |
| <pre>} CM.Phoenix.Model.v1.MeasurementLocation.PointPartMapping { pointIds (Array[integer], optional): IDs of the measurement points that are associated with this mapping, partIds (Array[integer], optional): IDs of the machine parts that are associated with this mapping }</pre> | | Response Conten Parameters Parameter M machineId | nt Type [application/json; v=1.0 v] Value (required) | Description Id of the machine | Parameter Type path | Data Type integer |

Power Cepstrum

- Power Cepstrum is a method for detection of periodicity in a frequency spectrum. This tool can be very useful for the analysis of machine failure vibration patterns which have multiple harmonics of fundamental frequency and/or sidebands, such as gearbox faults analysis.
- In this release, we added a new combined plot Spectra/Power Cepstrum manual frequency domain analysis and the ability to use Power Cepstrum data as a source for Diagnosis/Protean Diagnosis calculations.



Allow Running hours points to be used as trend source for software derived point

This feature was a customer request to help them calculate the remaining useful life KPI or the time to maintenance KPI.

- Added functionality that allows running hours to be used as a trend source in software-derived points.
- Running Hours point as well has a reset functionality for dropping the hours counter to a certain value.



OPC UA – Security modes for Internal OPC UA build-in server

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- Added OPC UA Security Modes and Access control for secure encrypted communication between Internal OPC UA server and external OPC UA Clients:
 - Now Observer's OPC UA Server supports: None/Sign/SignAndEncrypt security modes
 - Added supporting of None/UserNamePassword Access control modes
- Added selection of Hierarchy to be published in OPC UA server: Main Hierarchy or selected Workspace. This will help to reduce mount of data to be published and browsed by OPC UA clients for optimal performance and easier integration setup.
- OPC UA X.509 certificate management is arranged via the Monitor Service Manager application.

Note: For cloud installations, SignAndEncrypt security mode and UserNamePassword, access control mode only can be used.





OPC UA – Security modes for Internal OPC UA build-in clients

- Added OPC UA Security Modes and Access control for secure encrypted communication between Internal OPC UA clients to external OPC UA Server
- OPC UA X.509 certificate management is arranged via the Monitor Service Manager application

Note: For cloud installations, SignAndEncrypt security mode and UserNamePassword access control mode only can be used.

| OPC UA Windows Certificate Stor OPENSS Certificate Store Server Certificate Store Server.der Client.der | Server Certificates Export, Copy and Install Administrator Export, Copy and Install | OPC UA Client Windows Certificate Store or OPENSSL Certificate Store Certificate Store Certificate Store Client.der Server.der |
|---|---|--|
| OPC Server | | |
| Name | | |
| Server type: | OPC UA 🗸 | |
| Enabled: | | |
| Security mode: | SignAndEncrypt \lor | |
| Access control: | UserNamePassworc $ \smallsetminus $ | |
| Usemame: | | |
| Password: | | |
| Selected OPC server | | *Check |
| Scan interval | 0. | |
| | | |
| System log | | OK Cancel |

SKF @ptitude Observer Data Bridge: new OPC UA connector

- Data Bridge was initially added to Observer to allow remote connection to Observer databases by Microlog devices but was always intended as a tool to facilitate communication between Observer and many other types of system.
- In this release of SKF @ptitude Observer Data Bridge, we've added an OPC UA client consumer which allows you to collect data from local OPC UA Servers and proxy this traffic via encrypted MQTT protocol to @ptitude Observer backend.
- This option will be useful if the internet connection with the remote @ptitude Observer backend is not stable because the Data Bridge app has a data buffering capability. Or this direct connection via the internet is not allowed, so in Data Bridge can be used as a proxy from the customer network.
- In this release, we added a Linux version of this application with support for X and Y OS (this is a beta version of the app).





Phoenix API: new endpoint GET v1/gateways, GET v1/gateways/{id}/sensors

id

(required)

 Added new endpoints to help extract IMx-1 sensors information per IMx-1 Gateway



ID of the Enlight Collect

Gateway

path

integer

Phoenix API: new endpoint GET v1/deltasync

- A new endpoint was added to retrieve changes in DB based on change tracking (lastSyncPosition parameter).
- The data coming back from this new endpoint is exactly the same as the following endpoints (that exist in the documentation) and have the exact same configuration:
 - /v1/points/{pointid/diagnosesMeasurment
 - /v1/points/{pointid/trendMeasurement
 - /v1/points/{pointid/dynamicMeasurement
 - /v1/points/{pointid}

Example how to use the SyncPosition :

a. Ask *deltasync* , lastSyncposition =1, maxNumberOfRecords 100, typesToInclude = 2 (Trend)

b. The API will reply with a maximum of 100 records.

c. The last record *SyncPosition* is for example 4510. (the last record always has the highest *SyncPosition*)

d. The next query uses 4510 to get more new records if the number of records was 100 (if the number of records was less than 100 no need to ask for more)

e. Please note that the *SyncPosition* is per database not table so the *SyncPoistion* value can increase more than 100 in the example above.

Note:

Sync

- The retention time for the SQL sync is 7 days recommended to sync once per day.
- The Sync starts the first time anybody accesses the endpoint DeltaSync.
- Recommendation to sync each type by itself, Dynamic, Trend, Nodes, Diagnoses

| lastS | yncPosition | (required) | Client asking for changed data last queried sync position | query | long |
|----------|-------------------------|---|--|-------------------|---------------------|
| Param | eter | Value | Description | Parameter Type | Data Type |
| Param | neters | | | | |
| Respo | nse Content Type applic | ation/json; v=1.0 🗸 | | | |
| CMData | aServiceBase {} | | | | |
| CMD | ataServiceBase | | | | |
| Inline N | Nodel [| | | | |
| Model | Example Value | | | | |
| ок | , | | | | |
| Respo | onse Class (Status 200 |)) | | | |
| Get all | changes based on sync | ronisation position and choice. | | | |
| Impler | mentation Notes | | | | |
| GET | /v1/deltasync | End point to retrieve changes in database bas | sed on change tracking. Consumer i | needs to track c | hange tracking numb |
| | | | | | |

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Show/Hide List Operations Expand Operations



ENHANCEMENTS

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OPC UA server's Custom tags as a source for OPC points

- In previous Observer releases, OPC Points could use as a data source only OPC tags which were subscribed by Internal OPC UA Client. In this release, users can use Internal OPC UA server Custom Tags as a source for SW OPC Points as well. This should simplify the setup of scenarios when an external OPC UA client should push/write data to Observer's internal OPC UA server.
- Use the InternalOpcServer option for the OPC Server attribute in the OPC measurement point.



IMx-W/ IMx-S to IMx-8/IMx-16/IMx-16W configuration conversion

• Feature for conversion of old IMx device types configurations for making user's transition to latest IMx devices version smoother.

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Note: Once you've done the conversion, there is no functionality to revert it.

| General | | External communication | |
|-------------------|------------------------|------------------------|------------------------------|
| Number: | 3 (1-9999) | Type: None 🗸 | New IMx-Model |
| Name: | IMx-W | | IMx-16/IMx-16Plus |
| Model: | IMx-W \sim | | IMx-16/IMx-16Plus IMx-16W |
| Enabled: | \checkmark | | Analog Channel 01 |
| dentification | | | Analog Channel 02 |
| Serial no.: | 0 | | Analog Channel 03 |
| MAC Address: | | | Analog Channel 04 |
| Clear | Set detected device | | Analog Channel 05 |
| | | | Analog Channel 06 |
| Time preferences | | | Analog Channel 07 |
| torage schedule | offset: 12:00:00 AM 🚖 | | Analog Channel 08 |
| imeout comm.: | 0 Minutes | | Analog Channel 09 |
| onnection interva | l: 0 Hours | | Analog Channel 10 |
| | | | Analog Channel 11 |
| ime server (NTP | server) | | Analog Channel 12 |
| Same as mor | nitor server (default) | | Analog Channel 13 |
| Same as IEC | Server | | Analog Channel 14 |
| Use IP addre | ss: | | Analog Channel 15 |
| - | | | |

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Machine speed: Constant machine speed and SW speed handling

- To unify the way of handling configuration of machines with constant speed and making it a bit faster, we added an extra option in *Machine Properties Machine Speed tab* called *Constant Speed*. Now the user can enable it, and system automatically applies the specified input speed value for each stored vibration measurement.
- New setup for *Constant Speed* machines includes two steps:
 - In machine parts for Speed input location component, use default option Associated Speed used.
 - Enable in Machine Properties Machine speed option Constant Speed and define speed value to be used in (CPM)
- Constant speed option works with all main supported devices: *IMx-1, Microlog,* and IMx wired device family for both Trend and Dynamic measurements.
- With these changes, it's not mandatory to use associated SW speed points reference for each measurement point in constant speed machine configuration, but this old way of setup will remain for better user transition.
- Note: In case some measurement point requires another Associated Speed, the reference user can edit it within Point properties, so after that point's measurement will be excluded from *Constant speed* postprocessing and follow to new associated speed reference instead.
- Note: Only the machine's drivelines where *the* **Associated speed** used option is enabled for **Speed input** *location* will be calculated by this new feature. If some machine's drivelines have another reference, all related fault frequencies will be calculated by it.

| Indian type: Type: Calculated speed from spectrum O External speed input O Constant speed Constant speed value: 1470 [cpm] OK Cancel Machine properties X Name: Speed input location 2 Part number: Type: Meas. point Speed input location: Associated speed used Clear Simulation speed: 1 | ral Extende | ed Information Machine spe | Diagnosis | Protean Diagnoses | Attachments | Advanced | Machine parameters | Enlight Collect IMx-1 | System |
|---|---------------|--|-------------|-----------------------|-----------------------------|--------------|--------------------|-----------------------|--------|
| Inade Type: Calculated speed from spectrum © Etemal speed riput. @ Contart speed Contart speed value: 1470 (pm) | raction type: | | | | | | | | |
| Type: Calculated speed from specture | Enable | | | | | | | | |
| Constant speed value: 1470 [pm] | Type: | | O Calculate | d speed from spectrum | O Exte | mal speed in | put 💿 Ci | onstant speed | |
| Constant speed value: 1470 [cpm] | | | | | | | | | |
| OK Cerce Machine properties X Name: Speed input location 2 Part number: Part number: Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | Constant spe | eed value: | 1470 | [cpm] | | | | | |
| OK Carce Machine properties X Name: Speed input location 2 Part number: Part number: Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | | | | | | | | | |
| OK Can Machine properties × Name: Speed input location 2 Pat number: Type: Meas. point Speed input location: Associated speed used Clear Simulation speed: 1 | | | | | | | | | |
| OK Cancel Machine properties X Name: Speed input location 2 Part number: Part number: Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | | | | | | | | | |
| OK Cent Machine properties X Name: Speed input location 2 Part number: Image: Imag | | | | | | | | | |
| OK Canc Machine properties × Name: Speed input location 2 Part number: Type: Meas. point Speed input location: Associated speed used Clear Simulation speed: 1 | | | | | | | | | |
| OK Cance Machine properties X Name: Speed input location 2 Part number: Image: Ima | | | | | | | | | |
| OK Cancel Machine properties X Name: Speed input location 2 Part number: Image: Im | | | | | | | | | |
| OK Cance Machine properties X Name: Speed input location 2 Part number: Part number: Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | | | | | | | | | |
| OK Cancel Machine properties X Name: Speed input location 2 Part number: Part number: Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | | | | | | | | | |
| OK Carc Machine properties × Name: Speed input location 2 Part number: | | | | | | | | | |
| OK Carc Machine properties X Name: Speed input location 2 Part number: Part number: Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | | | | | | | | | |
| OK Carc Machine properties X Name: Speed input location 2 Part number: | | | | | | | | | |
| OK Cance Machine properties X Name: Speed input location 2 Part number: | | | | | | | | | |
| OK Cance Machine properties X Name: Speed input location 2 Part number: | | | | | | | | | |
| OK Cance Machine properties X Name: Speed input location 2 Part number: | | | | | | | | | |
| OK Cancel Machine properties X Name: Speed input location 2 Part number: | | | | | | | | | |
| Machine properties × Name: Speed input location 2 Part number: | | | | | | | | | |
| Machine properties × Name: Speed input location 2 Part number: | | | | | | | | 01 | 6 |
| Machine properties × Name: Speed input location 2 Part number: | | | | | | | | ОК | Canc |
| Machine properties X Name: Speed input location 2 Part number: | | | | | | | | ОК | Canc |
| Name: Speed input location 2 Part number: | | | | | | | | ОК | Cano |
| Name: Speed input location 2 Part number: | | Machine prop | perties | | | | | ок | Canc |
| Name: Speed input location 2 Part number: | | Machine prop | perties | | | | | ок | Cano |
| Part number: Image: Meas. point Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | | Machine prop | perties | Granding | 4 10 0 04100 | - 2 | | ок | Cano |
| Type: Meas. point Speed input location: Associated speed used Clear Simulation speed: 1 | | Machine prop | oerties | Speed input | ut location | 12 | | ОК | Cano |
| Type: Meas. point Speed input location: Associated speed used Simulation speed: 1 | | Machine prop Name: | oerties | Speed input | ıt locatior | 12 | | ОК | Cano |
| Speed input location: Associated speed used Clear Simulation speed: 1 | | Machine prop Name: Part number: | perties | Speed inpu | ut location | n 2 | | ОК | Canc |
| Speed input location: Associated speed used Clear Simulation speed: 1 | | Machine prop Name: Part number: Type: | perties | Speed inpu | ıt locatior | 12 | | ОК | Cano |
| Simulation speed: | | Machine prop Name: Part number: Type: | perties | Speed input | ut location | 12 | | ОК | Canc |
| Simulation speed: | | Machine prop Name: Part number: Type: Speed input k | perties | Speed input | t location t | n 2 sed | | ок × | Cano |
| | | Machine prop Name: Part number: Type: Speed input lo | perties | Speed input | ıt locatior t speed u | n 2 sed | | ок × | Cano |

Cancel

Access to Trend/Diagnosis/Protean plots from full screen mode of Process overview

 In this version, users with Machine Operator 1 role can choose between different plots in the Process overview, including Trend/Diagnosis/ Protean diagnosis plot. This feature should help operators get access to the measurement's history to check trends behavior.



Phoenix API: v1/captures/{captureId} added speed Pulses, associated Process/Digital parameters

- SpeedPulses array, associated Process/Digital measurement for each event capture chunk now included in the API response.
- Issue with incorrect timestamps has been resolved, so now the parameter *begin* = start of the first chunk, and parameter *end* = end of the last chunk in Event Capture.

For more information and examples, please check Phoenix API specification for SKF @ptitude Observer v13.3

| GET /v1/captures/{captureld} | Retreives one capture |
|---|-----------------------|
| Implementation Nator | |
| This call returns a list of measurement information for a apositic capture | |
| This call returns a list of measurement mormation for a specific capture | |
| Response Class (Status 200) | |
| ОК | |
| Model Example Value | |
| Inline Model [| |
| Measurement | |
|] | |
| Measurement { | |
| euType (integer, optional): Internal point engineering units, see EUType, | |
| timewave (Array[number], optional): List of floats with timewave measurment data, | |
| speedPulses (Array[number], optional): List of integer with speed pulse data, | |
| speedMeasurements (Array[number], optional): List of floats with speed measurement data, | |
| processMeasurements (Array[number], optional): List of floats with process measurement data, | |
| digitalMeasurements (Array[integer], optional): List of integers with digital measurement data, | |
| scaleFactor (number, optional): Timewave measurement scaling factor, | |
| begin (string, optional): Date when measurement was started (UTC), | |
| triggered (string, optional): Date when measurement was triggered (UTC), | |
| end (string, optional): Date when measurement was ended (UTC), | |
| pointID (integer, optional): Database ID of the point, | |
| name (string, optional): Name of the capture point, | |
| comment (string, optional): Comments about the capture point, | |
| Id (integer, optional): Datbase ID of the capture point, | |
| src (string, optional): API source string for retreiving measurement point information, | |
| lines (integer, optional). Reason why the capture has higgered, | |
| samplingErequency (number optional): The configured sampling frequency for the capture group | |
| sampling requercy (number, optional). The computed sampling requercy for the capture group | |
| 3 | |

IMx-1 ATEX version sensors

- In this Observer version, the user will be able to identify a newly introduced IMx-1 -EX version sensors (CMWA 6100-EX) within IMx-1 System View, in order to understand future battery-life trends.
- Recommended FW version for CMWA 6100-EX sensor v 4.1

| Enlight Collect I | Mx-1 System View | | | | | | | | | | | | | |
|-------------------|----------------------|---------------|-------------------------|------------------|--------------|------------------|----------|--------------|-------------------------|------------------|-------------|-------------|------|---------------------|
| Gateways | | | | | | | | | | | | | | |
| Name | Hardware ID | Location | Self diagnostics status | Synchronized | Connection | Firmware version | Sensors | Ex Sensors | IP address | | | | | |
| Gateway E4 | 00-01-B9-69-00-E4 | Test Lab 3302 | OK | In progress | Connected | 4.0 | 13 | . 0 | 192,168,1,197 | | | | | |
| Gateway 0A | 00-01-B9-69-01-0A | Test Lab 3302 | OK | Yes | Connected | 4.0 | 9 | 2 | 192.168.1.94 | | | | | |
| | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |
| | | | | | | | | | | | | | | |
| | | _ | | - | 1 | | | | | | | | | |
| New | Edit | Del | ete Sync | chronize | | | | | | | | | | |
| | | | | | - | | | | | | | | | |
| | | | | | | | | | | | | | | |
| Sensor informa | tion Mesh statistics | 3 | | | | | | | | | | | | |
| | | | | | | | | | 0 | | | B | - | 1 |
| Name | Hardware II | D Locat | ion | | | Self diagnostics | s status | Synchronized | Connection | Firmware version | Sensor Mode | Battery (%) | Ex | Last seen |
| IMx-1 Sensor | 5:86 C4-BD-6A-0 | 0-05-86 Compa | any\Test Machine #3\As: | et\IMx-1 Sensor | 5:86 | OK | , | Yes | OK | 4.1 | Leaf | 46 | | 2023-04-19 14:00:39 |
| IMx-1 Sensor | 4E:15 C4-BD-6A-0 | D-4E-15 Compa | any\Test Machine #3\Ass | et\IMx-1 Sensor | 4E:15 | OK | , | Yes | Temporarily unreachable | 4.1 | Mesh | 57 | | 2023-04-19 12:27:24 |
| IMx-1 Sensor | F9:3C C4-BD-6A-0 | 0-F9-3C Compa | any\Test Machine #4\As | set\IMx-1 Senso | F9:3C | OK | , | Yes | OK | 4.1 | Leaf | 99 | | 2023-04-19 12:30:40 |
| IMx-1 Sensor | 4D:F5 C4-BD-6A-0 | 0-4D-F5 Compa | any\Test Machine #4\Ass | et\IMx-1 Sensor | 4D:F5 | OK | , | Yes | OK | 4.1 | Leaf | 58 | | 2023-04-19 12:27:23 |
| IMx-1 Sensor | 4D:F0 C4-BD-6A-0 | 0-4D-F0 Compa | any\Test Machine #3\As: | set\IMx-1 Sensor | 4D:F0 | OK | | r'es | Temporarily unreachable | 4.1 | Mesh | 53 | | 2023-04-19 13:00:29 |
| Relay 1 | C4-BD-6A-0 | 0-4E-08 Commi | ssioned by Android App | | | OK | ` | Yes | Temporarily unreachable | 4.1 | Relay | 58 | | 2023-04-18 17:08:51 |
| Relay 2 | C4-BD-6A-0 | 0-F7-84 Commi | ssioned by iOS App | | | OK | ` | Yes | Temporarily unreachable | 4.1 | Relay | 99 | | 2023-04-19 12:57:42 |
| IMx-1 ATEX 1 | 5:45 C4-BD-6A-0 | 1-15-45 Compa | any\Test Machine #5\Ass | et 2\IMx-1 ATE | < 15:45 | OK | ` | Yes | OK | 4.1 | Mesh | 99 | €⊋ | 2023-04-19 12:27:31 |
| IMx-1 ATEX 1 | 5:41 C4-BD-6A-0 | 1-15-41 Compa | anv\Test Machine #5\AT | EX Sensors\IMx | 1 ATEX 15:41 | OK | N 1 | Yes | ок | 4.1 | Mesh | 98 | (Ex) | 2023-04-19 12:27:34 |



BUGS

*Not all bugs are listed in presentation, list you can find in change log on

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IMx-1 : Hierarchy icons not updated in workspace and process overview

• Fixed an issue with IMx-1 points not having their status updated correctly when visualised in a workspace or the process overview.



- The process view colour will now follow the hierarchy tree colour.
- IMx-1 points will be updated in a 20-30 seconds interval when shown in the process overview.

Microlog : "last value" not correct

• Fixed an issue that would cause Microlog not to download the correct last value on points.

• This issue is now fixed and last value will be displayed correctly (as it did before 13.2).





Microlog: Not possible to have different speed source for two chains

• Fixed a bug where having two machine chains using different speed inputs would break the fault frequency calculations



• The left one worked, while the right one would break the fault frequency calculation.

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Microlog: Default speed

- Fixed an issue with Microlog spectra's where using 'set speed' or 'default speed' in combination with 'constant speed' or any associated machine part speed would incorrectly calculate fault frequencies.
- The issue would occur if the machine part input location was set to Microlog tacho and Acceleration point was using the default speed or set speed function. And would cause the diagnosis and plot not to show fault frequency.

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Data Bridge route download

- If a user downloaded routes through Data bridge to a Microlog device with existing routes, the data would be overwritten. This posed a risk that data would be unintentionally lost.
- Now, if measurement data exits on the route in the Microlog, a warning is added when trying to update a route to Microlog. This prevents data to be overwritten.

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Data bridge: Broken hierarchy on Microlog

- The issue was that when downloading routes to Microlog, the hierarchy on the Microlog was not displayed correctly, and points would be missing from the hierarchy. Editing end freq (from 20-50 Hz, for example) would cause the point to be transferred correctly.
- But this issue is now fixed and now editing should be needed.

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Data bridge incorrect timestamp

 Fixed an issue that would cause a mismatch in time zones between Data Bridge and Microlog. This would happen when getting measurement data from Microlog because the UTC time needed by Observer was not converted properly.

MPUW:

- Fixed a crash that would occur when using Multiple Point Update Wizard to edit IMx Process points linked to a Modbus register.
- Fixed a crash in Multiple Point Update Wizard when trying to edit Gear Inspector or Time Waveform Analysis points.
- Fixed a crash in Multiple Point Update Wizard when trying to edit Speed points.
- Fixed an issue which enabled setting incorrect configurations on IMx-1 points through multiple point update wizard (In the report, the user was able to set fmax up to 6400 for IMx-1).

External database cause Observer to enter "not responding" state

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• Fixed an issue where Observer would freeze in case any external databases were unreachable.

• For a full list of fixed bugs, see the change log.



Rail Track Monitoring release summary

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NEW FEATURES

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Observer

Integration of Observer with Rail GEN2 backend:

- User should be able to select which Rail Gen2 companies they want to see in the Observer hierarchy.
- All vehicles/assets automatically visible in the Observer hierarchy, for selected company(s).
 - Vehicle changes made in Gen2 (naming etc.), automatically propagate to the Observer hierarchy
- Sensor measurement data automatically shown in Observer
 - Battery Voltage
 - Speed
 - Bearing (Env3)
 - Wheel Flat
 - Raw (Acceleration)
 - Temperature
- All sensor measurement data should be visible in Observer, even if not received in time-sequenced order.
- IRAD/IRSA Alarms in Observer.
- Create Alarms on the basis of event cases.



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APIs

3 new APIs are added for implementing the features of Televic MVP:

- <u>/v1/insight/vehicle</u> Create and update vehicles and their information.
- <u>/v1/insight/telemetry</u> Update sensor measurement data.
- /v1/insight/getNodeIDAndNodeName Returns ID and names of measurement points under machines with the help of which alarms are created using Alarm API.

Prerequisites:

Before any vehicle can be imported into @Observer, a template for that vehicle must first be created and appended to the template library.

Vehicle API

Create a vehicle/asset or Update vehicle/asset details received from Rail Gen2 companies in Observer.

| POST /v1/insight/ | /vehicle | | | | | |
|--|---|-------------------------------------|---|-----------------|------|---------------------------|
| | Recieves Vehicle commission CREATE or UPD. | ATE from Insight Rail Clo | oud Example URL for call: http://localhost:50000/api/ | Insight/vehicle | | |
| Response Class (S OK | Status 200) | | | | POST | /v1/insight/commissionVel |
| Model Example Val | lue | | | | POST | /v1/insight/updateVehicle |
| { "message": "stri } | ing" | | | | | |
| tesponse Content T Parameters | Type application/json; v=1.0 | | Parameter | | POST | /v1/insight/vehicle |
| commission { "r 87d1 "s "d "d "d Parar appli | reference": "bdc2d831-fc62-47a4- 1-e75b7c590h87", setId": "TRAIN TestDemoNew", designation": "TRAIN TestDemoNew", description": "Gen1 imported meter content type: lication/json; v=1.0 | RailCloud t Commission object | Type Data Type body Model Example Value { "SetUIC": "string", "SetId": "string", "OEM": "string", "Designation": "string", "Description": "string", "Classification": "string", "Coupling": "string", "Coupling": "string", "CurrentStatus": "string", "Carriages": [| | | |
| Response Messag | ges Reason | Response Model | | Headers | | |
| 204 | The request was successfully completed but no content found. | p | | | | |
| 400 | The request was invalid | Model Example Value | | | | |

JSON

file

```
"reference": "bdc2d831-fc62-47a4-87d1-e75b7c590h87",
"setId": "TRAIN TestDemoNew",
"oem": "KVB",
"designation": "TRAIN TestDemoNew",
"description": "Gen1 imported vehicle: 43663",
"classification": "MultipleUnit",
"coupling": "Coupled",
"currentStatus": "InService",
"carriages": [
    "evn": "D99911",
    "position": 1,
    "vehicleNumber": "TRAIN TestDemoNew-01",
    "wheelSets": [
      "6bc5bd43-fe33-4f7f-a8bd-40ea4abd382f",
      "b5e02100-d858-40db-b41d-8c3de5d52d51",
      "041413d6-c826-4a6d-89ad-180ae540fa7b",
      "16fda0fb-bd0a-46bf-ba15-df2ec7972655"
   ],
    "reference": "c9f4fd18-3ac9-433c-9f11-f7080af62a22"
  ł.,
    "evn": "D84805",
    "position": 2,
    "vehicleNumber": "TRAIN TestDemoNew-02",
    "wheelSets": [
      "4529fb30-88ba-4180-8da3-067f61a3f02f",
     "8e26469f-15f7-4306-9f4e-4586c5fa9cd5",
      "187d5801-ff01-427d-afee-edf4b354c604",
     "e0508413-52a7-4eaf-aaf1-54861c191e1b"
    ],
    "reference": "c01cdab5-1f7f-4c0a-afdb-d18f81d40277"
    "evn": "N5380",
    "position": 3,
    "vehicleNumber": "TRAIN TestDemoNew-03",
                                                                           length: 117,303 lines: 3,724
```

Observer

SKF

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| 11 | л» - | | | | - | |

Post Telemetry API

Update Sensor measurement data in Observer.

| POST /v1/insight | /telemetry | | Saves a new dynamic measurement into the databa | se 📄 🖷 🖲 🛄 TRAIN TestDemoNew |
|--|---|--|--|---|
| Implementation No Updates the measur Response Class (3 OK Model Example Va | otes rements of the speed, temperature, raw dat Status 200) lue | a, envelope, wheelflat and battery | / points | TRAIN TestDemoNew-01.1. TRAIN TestDemoNew-01.1. TRAIN TestDemoNew-01.1. TRAIN TestDemoNew-01.2. TRAIN |
| {} | | | | Battery |
| Response Content 1 | Type application/json; v=1.0 | v | | TRAIN TestDemoNew-01.2. |
| Parameters | | | | TRAIN TestDemoNew-01.3. |
| Parameter Valu | е | Description Paramete Type | ^r Data Type | 1 40 10 10 |
| measurement { "" e75 " afe " Para app | tenantid": "volatiletesttenant", vehicle": "bdc2d831-fc62-47a4-87d1- b7c590h76", wheelset": "187d5801-ff01-427d- e-edf4b354c604", axlebox": "d1cbf86c-2bca-4eed-92ba- ameter content type: blication/json; v=1.0 v | Data Service body Measurement object | <pre>Model Example Value { "values": [{ "timestamp": 0, "identifier": "string", "energy_remaining": { "units": "string", "value": 0 }, "v_0": { "units": "string", "units": "string", "units": "string", "value": 0 }, "v_0": { "units": "string", "units", "string",</pre> | |
| Response Messag | jes | | | |
| HTTP Status Code | Reason | Response Model | Heade | rs |
| 204 | The request was successfully completed but no content found. | | | |

RH A н RH A LH A RH A

JSON



Observer



SKF

Generate alarms in Observer using the alarm API – GetNodeIDAndNodeName

To generate alarms in Observer, we use v2/alarms under alarms API. This endpoint accepts pointID as an input parameter, but other systems will not know the

SKF

exact PointID of the measurement point because the IDs are internal to Observer.

Hence, we use this new API to accept Vehicle ID, WheelsetID and Axlebox ID and return the pointID and pointName corresponding to it so then this returned ID can be used to create alarms in Observer.

| GET | /v1/insig | nt/getNodeIDAndNodeName Re | turns Node | eld and NodeName correspond | ng to the VehicleID | , WheelsetID and Axlebox | ID passed. |
|-------------|-------------|--|------------|---|---------------------|--------------------------|------------|
| Respo OK | nse Class | (Status 200) | | | | | |
| Model | Example \ | /alue | | | | | |
| {} | | | | | | | |
| Respor | nse Conten | t Type application/json; v=1.0 ∨ | | | | | |
| Param | eters | | _ | | | | |
| Parame | eter \ | /alue | [| escription | Parameter Type | Data Type | |
| vehicl | eID | bdc2d831-fc62-47a4-87d1-e75b7c590h87 | | | query | string | |
| wheels | etID | 6bc5bd43-fe33-4f7f-a8bd-40ea4abd382f | | | query | string | |
| axlebo | TD | 06d68ac9-48cf-42ee-b973-70b811b6f9d7 | | | query | string | |
| Respo | nse Mess | ages | | | | | |
| HTTP S | Status Code | Reason | Res | ponse Model | | | Headers |
| 204 | | The request was successfully completed no content found. | l but | | | | |
| 400 | | The request was invalid | Mod | el Example Value | | | |
| | | | { | "message": "string", "messageDetail": "string" | | | |

Observer TrendList without Insight Rail license

| ierarchy System Workspace Diagram RailMo | | | | 1004 | | | Contraction of the | |
|--|---|-------------|----------------------|-------|---------|---------|--------------------|---------|
| 🖕 🗢 📗 TRAIN TestDemoNew | ~ | Meas. point | Date/Time | Speed | Process | Digital | E.U. | Overall |
| 🖮 🕼 😥 TRAIN TestDemoNew-01.1.LH 🔒 | | Envelope 3 | 3/26/2023 5:00:29 AM | 39 | 0 | 0 | gE P | 0.094 |
| 🕀 🔐 😥 TRAIN TestDemoNew-01.1.RH | | Envelope 3 | 3/26/2023 4:00:29 AM | 39 | 0 | 0 | gE P | 0.094 |
| 😑 💮 TRAIN TestDemoNew-01.2.LH 🖪 | | Envelope 3 | 3/25/2023 9:40:00 AM | 39 | 0 | 0 | gE P | 0.094 |
| I Speed | | Envelope 3 | 3/25/2023 5:00:29 AM | 39 | 0 | 0 | gE P | 0.094 |
| | | Envelope 3 | 3/24/2023 4:00:29 AM | 39 | 0 | 0 | gE P | 0.094 |
| • 🔘 Temperature | | | | | | | | |
| 🕀 🔘 Wheel flat | | | | | | | | |
| Battery | | | | | | | | |

Observer TrendList with Insight Rail license – SensorIdentifier column is added to the TrendList.



| Meas. point Date/Time Speed Process Digital E.U. Overall Sensor Identifier Envelope 3 3/26/2023 5:00:29 AM 39 0 0 gE P 0.094 IMEI35936809048919 Envelope 3 3/26/2023 4:00:29 AM 39 0 0 gE P 0.094 IMEI35936809048919 Envelope 3 3/25/2023 9:40:00 AM 39 0 0 gE P 0.094 IMEI35936809048919 Envelope 3 3/25/2023 9:40:00 AM 39 0 0 gE P 0.094 IMEI35936809048919 Envelope 3 3/25/2023 5:00:29 AM 39 0 0 gE P 0.094 IMEI35936809048919 Envelope 3 3/24/2023 4:00:29 AM 39 0 0 gE P 0.094 IMEI35936809048919 Envelope 3 3/24/2023 4:00:29 AM 39 0 0 gE P 0.094 IMEI35936809048919 Envelope 3 3/24/2023 4:00:29 AM 39 0 6 6 6 6 6 Envelo | | 1 | 1 | 1 | 1 | | 1 | |
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| Envelope 3 3/24/2023 4:00:29 AM 39 0 0 gE P 0.094 IMEI35936809048919 | Envelope 3 | 3/25/2023 5:00:29 AM | 39 | 0 | 0 | gE P | 0.094 | IMEI359368090489199 |
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| Image: Constraint of the second sec | | | | | | | | |
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Observer Meas. Date page without Insight Rail license





Observer Meas. Date page with Insight Rail license – SensorIdentifier column is added to the table.

| Hierarchy System Workspace Diagram RailMo | - Envolopo 2 | | | | | | | | | | | | |
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| □- 😌 🧃 Company 🔨 | Path Company\TRAIN TestDemoNew\TRAIN TestDemoNew-01.2.LH\Envelope 3 | | | | | | | | | | | | |
| 🗄 🔛 🎡 TRAIN TestDemoNew-01.1.LH 🛕 | Туре | Envelop | е | Dad | TR | AIN TestDemoNe | w-01.2.L⊦ | ne TRAIN TestDemo | New-01.2.LH | | | | \bigcirc |
| 🖶 🕎 🎡 TRAIN TestDemoNew-01.1.RH 🛕 | Number | 5 (5) | | | | | | | | | | | |
| 🖨 😌 🎡 TRAIN TestDemoNew-01.2.LH 🛕 | | - (-) | | | | | | | | | | Op | an point |
| - I Speed | | | | | | | | | | | | | |
| - (C) O Envelope 3 | Measuremen | ts | | | | | | | | | | | |
| | | | - | | • | | | | | | | | |
| 🐨 🥥 Temperature | iverall [gE P] | Speed (Delta) | Process (Delta) | Digital | Storage reason | Data type | Average | Exclude from diagnosis calculation | Keep forever | Buffer | Measurement Comment | Sensor Identifier | <u></u> |
| (C) 🔘 Wheel flat | .09420946 | 39 | 0 | 0 | Scheduled | Time waveform | 0 | No | No | Normal | . INSIGHT ENVELOPE GE3 DATA | IMEI35936809048919 | |
| Battery | .09420946 | 39 | 0 | 0 | Scheduled | Time waveform | 0 | No | No | Normal | . INSIGHT ENVELOPE GE3 DATA | IMEI35936809048919 | 3 |
| 🕀 🕼 🖗 TRAIN TestDemoNew-01.2.RH 🛕 | .09420946 | 39 | 0 | 0 | Scheduled | Time waveform | 0 | No | No | Normal | . INSIGHT ENVELOPE GE3 DATA | IMEI35936809048919 | 7 |
| 🖶 😍 🎡 TRAIN TestDemoNew-01.3.LH 🔺 | .09420946 | 39 | 0 | 0 | Scheduled | Time waveform | 0 | No | No | Normal | . INSIGHT ENVELOPE GE3 DATA | IMEI35936809048919 | 3 |
| 🕀 🕼 🕼 TRAIN TestDemoNew-01.3.RH | .09420946 | 39 | 0 | 0 | Scheduled | Time waveform | 0 | No | No | Normal | . INSIGHT ENVELOPE GE3 DATA | IMEI35936809048919 | 3 |
| E 🕼 🖗 TRAIN TestDemoNew-01.4.LH 🔺 | | | | | | | | | | | | | |

Web Client

Add a switch to toggle between an aggregated (with counter) and non-aggregated view in the Noise Monitoring application.

In the noise monitoring application, we have added a switch to enable/disable aggregated view. If it's aggregated view, it is with counters. Else it will show a single marker with direction.



With Aggregated view switched off, we can see individual single markers with direction.

SKF

Map

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6.

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DENTHAL Aachener Str.

Stadionbad Hallenbad

)GELSANG GE BICKENDORF

Status Type

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a&o Hostel

MAURITIUS-VIERTEL

Hiroshima-Nagasaki-Park

CÄCILIEN-VIERTEL

Schokoladenmuseum

Map data ©2023 GeoBasis-DE/BKG (©2009), Google

Terms of Use Report a map erro

Köln

(evhoard shortcuts

SKF



BUG FIXES

Noise Monitoring web UI reporting unreasonable speeds

2021-02-12 07:00:02

2021-02-12 07:00:02

2021-02-12 05:00:01

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NA

272.69

283.18

239.73

Web UI is reporting speeds over 500 km/h, which is unreasonable. There is a conversion required from CPM(Cycles per minute) to km/hr. Currently, we have modified the web client UI to show the correct unit as configured in Observer.



Measurement Details Measurement date 2021-02-09 15:00:16 Noise amplitude per track side [m/s^2 PtP] 0.08049388 Speed [Cycles per minute] 129.7242 Direction NA System Information Mic Point Name RS3_R_MIC test bitte anlassen

Measurement Details

SKF

Changes for performance issue fix – Data delay for 3-4 days

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This was a customer issue where we found there was a data delay for 3-4 days with the following performance issue. There was a DB Null conversion error, and the measurement buffer was set to 12 months. Buffer is now set to 1 day, and conversion is taken care of.



CPU load close to 100%



Error:

 2022-07-14 09:30:04(UTC) Runtime Error. System.OverflowException: Arithmetic operation resulted in an overflow. at CM.MonitorCore.CMRailMoCalc.EstimateTimeStampsAndSummarizeDataForMetersTravelled(CMDbProviderFactory dbFactory, CMRailwaySectionCaptureE railwaySectionCapture) at CM.MonitorCore.CMRailMoCalc.InitSummaryCalculation()
 2022-07-14 09:30:04(UTC) Internal. 13.2.194.0 ***SYSTEM STOPPED*** (Reason : Error)

Quick fix / Workaround:

•SELECT * FROM RailwaySectionCapture where Processed = 0 and CalculatedDistance >0 and RailSettingIDNode >0 •Update RailwaySectionCapture set Processed=1 where Processed = 0 and CalculatedDistance >0 and RailSettingIDNode >0

Fix:

Added null checks and checks for variables used for divided by zero values to fix arithmetic overflow exception.

Issue:

The captures were "discarded" based on the current day. If buffered data was arriving, a lot was "discarded".

Not a bug in IMx.

IMx will continue to store as long the memory can store a complete capture.

Example

IMx day 1, storing 300 capture, communication to monitor ok. Monitor stores 50 and truncate 250

IMx day 2, storing 300 capture, communication to monitor Not ok.

IMx day 3, storing 300 capture, communication to monitor Not ok.

IMx day 4, storing 35 capture, memory full, communication Not to monitor ok.

IMx day 5, storing 0 capture, communication to monitor Not ok.

Communication back, Monitor stores 50 captures form day 2 and truncate the rest.

IMx day 6, storing 300 capture, communication to monitor ok. Monitor stores 50 and truncate 250

Monitor should store IMx day 1, Monitor stores 50 Communication back day 5 Monitor stores 50 captures form day 2 Monitor stores 50 captures form day 3 Monitor stores 35 captures form day 4 Monitor stores 0 captures form day 5

Fix:

Changes are made in the method used for EventCapture count for the present day. The time was always counted from the present day 12AM and not from the time that monitor had stopped working.

Issue:

Error message comes also when the user clicks on all 0 points along one record from left to right, not only in the left or right corner. Furthermore, it looks like there is some faulty "0" data coming into the database.

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Fix:

Adding checks in all places where there were properties of objects being accessed. We check for the object being null and only then access the property.

