

SKF @ptitude Observer v13.2.1 release summary

Requirements

Software and FW requirements

- Recommended IMx-1 GW firmware version 3.5
- Recommended IMx-1 Sensor firmware version 3.4
- Recommended IMx firmware version 7.8



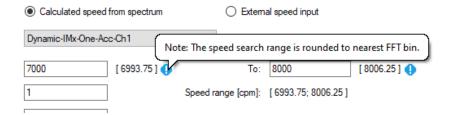
Resolved bugs

- VSTS#296525 Resolved an issue with the Set Speed function in the FFT plot, which is causing unhandled exceptions for a few UI languages
- VSTS#301321 Resolved bug in Multiple Point Update Wizard, which causes application crash after an attempt to update F1 type parameter in Dynamic Envelope Order tracking points
- VSTS#310220 Resolved an issue with the Calculated Machine Speed feature when post-processing sometimes not finishing for the External speed input option
- VSTS#253430 Resolved an issue when Auto scaling in Trend Plot does not consider custom band's trend values
- VSTS#304345 Resolved an issue with parameter Max.numbers of measurements for diagnosis recalculations (Options/Data), which always applies as hardcoded 40000 and can cause performance issues in large databases. Now editing of this parameter works as it should
- VSTS#303239 Resolved an issue with Modbus Export function, which is preventing F1-F5 data sharing in case Custom Bands enabled in IMx8 point
- VSTS#337988 Software speed on machine parts does not work for Microlog points in Observer 13.2
- VSTS#337988 Fixed an issue where Microlog points would no longer receive speed values if they came from a software derived speed point



Enhancements and optimisations

- VSTS#304346 Optimisation of Alarm list handling in Observer makes Acknowledging Alarms process several times faster.
- VSTS#304399, 304402 Optimisation of IMx-1 sensor configuration handling in Observer, which before caused high consumption of RAM and enormous load for SQL Server for large installations with few hundreds of IMx-1 sensors per database.
- VSTS#306721 Small UI changes of Machine Speed tab UI





Rail Track Monitoring features

Web client

- VSTS#254300 The map does not zoom out and stays at the same zoomed points in Google maps if the user re-applies the filter
- VSTS#303845 Travel direction of measurement points to be shown in noise monitoring application (requires IMx FW 7.8) filter

Phoenix API

 VSTS#180734 – API changes to fetch direction from firmware and return to web client in Noise monitoring application

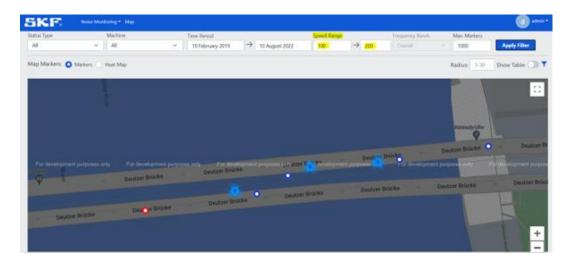
Bug Fixes (Web client)

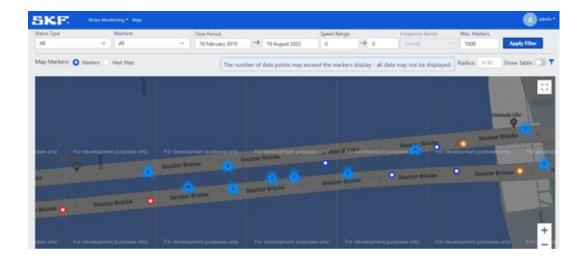
- VSTS#302319 Metro: Record correction action is unable to save the action for Defect not fixed
- VSTS#303477 The calendar is hiding behind the banner



The map does not zoom out and instead stays at the same zoomed points in Google maps if the user re-applies the filter

If the user zooms in for a particular measurement point and then changes any of the filter settings and re-applies the filter option, the Google map zooms out, and all the measurement points would appear. Instead, the map should stay at the same zoomed points and disappear if it does not fall under the conditions of the applied filter.



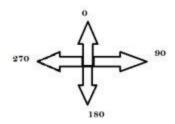




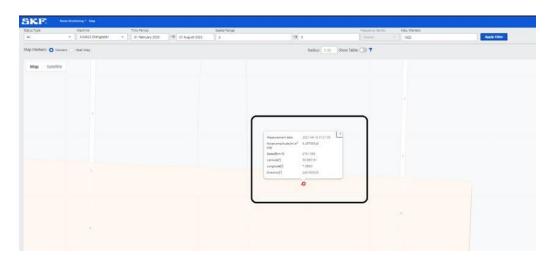
Travel direction of measurement points to be shown in noise monitoring application

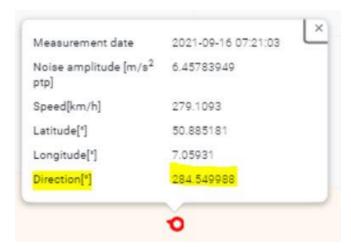
For the noise monitoring application, the users can now also see the direction in which the tramway travels. The measurement point, if zoomed, has a pointed arrow that indicates the direction in which the vehicle is moving.

The direction is indicated, keeping the below thumb rule in consideration.



This is how the points would look in the web client and on hover. The measurement details popup also displays **Direction** as a newly added parameter.







API changes to fetch direction from firmware and return to web client in Noise monitoring application

Firmware changes were done to add the direction of travel in the GPS location (requires external communication module GPS50M) and return in the **gpsloc** parameter.

IDMeasurement	Comment
393268	+50.937247+006.971142+0057/01.2/055613/011.7/031.4
393267	+50.937142+006.971061+0060/01.4/055611/014.9/046.9
393266	+50.937061+006.970916+0061/01.4/055609/017.2/050.3
393265	+50.937018+006.970823+0062/01.2/055608/016.4/056.2

Related API changes arere done in the **shocksAmplitude** to fetch this direction from **MeasurementInformation** table and return so that this parameter can be used to display the direction of travel of these points in the corresponding Noise monitoring web application.

GET /v1/mainline/{machineld}/shocksAmplitude

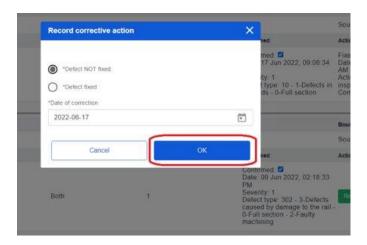
List noise amplitude of machines.

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Idpoint (nteger, optional). OPont
Idmessurement (integer, optional): ICMsesurement,
micName (string options). Name of the train,
machineld (integer, optional) to of the machine.
latitude (number, optional); Listitude
longitude (number, optional): Longitude
numberOfCustomBands (integer, optional); Number of Bands.
speed (number, optional). Speed.
readingTime (string, optional). ReadingTime of trend,
frequencybandtamp (number, optional), Frequency of Bond's,
frequencybandZamp (number, optional), Frequency of Band2,
frequencyband3atep (number, optional). Frequency of fland3
frequencybend4emp (number, options/): Frequency of Band4,
everal/Amplitude (numbur, optional), Amplitude,
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frequencyband2Name (string, uploos). Name of 2nd bequencyband.
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frequencyband#Name (string, spoorse). Name of 4th frequencythand,
overalthrquencybandName (string, optional). Name of 5th frequencyGand
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enableAlarmF1 (boolean, optional): Enable Alarm F1
enableAlarmF2 (coolson, optional): Enable Alarm F2
enableAlarerF3 (boolean, optional) Enable Alarm F3.
overal@nableAlarm (books); colonal; Enable Alam F3.
warningLevelF0 (number, options). Warning Level F0,
warningLevelF1 (number, optional). Warning Level F1
warningLevelF2 (number, optional). Warning Level F2.
warningLevelF3 (number, optional). Warning Level F3
overall/NamingLevel (number, optional): Warring Level F-4.
starreLevelF0 (number, optional). Alarm Level F0.
starreLevelF1 (number, optional). Alarm Level F1.
atares.evelF2 (number, optional). Alarm Level F2
alarmLevelF3 (number, optional). Alarm Level F3.
everal(AlarmsLevel (number, optional): Alerm Level F4.
                         of Direction of the measu
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Metro: Record correction action is unable to save the action for "Defect not fixed"

Application was unable to save the "record correction action" for defect not fixed, which is now resolved.



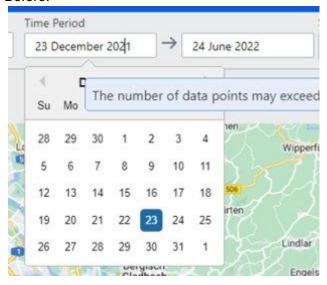




Calendar was hiding behind the banner in Noise monitoring application

The user was unable to modify the month from the banner because it was hiding behind the banner, which is now resolved.

Before:



After:

